## **OIDOJATACO**

## **DSE0420**

## OEM Area Imager Decoded Scan Engine





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#### Patents

This product is covered by one or more of the following patents:

Utility patents: EP0996284B1; EP0999514B1; EP1128315B1; EP1172756B1; EP1396811B1; EP1413971B1; EP1804089B1; EP1828957B1; EP2315156B1; JP4435343B2; JP5192390B2; US6478224; US6512218; US6513714; US6561427; US6808114; US6877664; US6997385; US7053954; US7234641; US7387246; US7721966; US8113430; US8245926; US8561906; US8590795; ZL200680050007.8.

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### **Table of Contents**

PREFACE       V         About this Manual       V         Manual Conventions       V         Outline       V         Technical Support       Vi         Datalogic Website Support       Vi         Vereine       Vi         Reselfer Technical Support       Vi         MECHANICAL CHARACTERISTICS       1         Overview       1         Key Parameters       2         Dimensions       2         OPTICAL CHARACTERISTICS       3         Mey Parameters       2         Dimensions       2         OPTICAL CHARACTERISTICS       3         Mey Parameters       2         Mining System       4         Alming System       4         Alming System Parameters       4         Regulatory       4         Alming System Parameters       5         Reading Performances       6         Test Conditions       7         Avianding System Parameters       7         Avianding System Parameters       7         Vindow material       7         Nicolum material       7         Vindow material       7         Vindow material <th>INTEGRATOR SOFTWARE LICENSE AGREEMENT</th> <th> III</th>	INTEGRATOR SOFTWARE LICENSE AGREEMENT	III
About this Manual       v         Manual Conventions       vv         Outling       vv         Technical Support       vv         Technical Support       vv         MECHANICAL CHARACTERISTICS       1         Ourriee       1         MECHANICAL CHARACTERISTICS       1         Ourriee       1         MECHANICAL CHARACTERISTICS       1         Ourriee       1         Key Parameters       2         Dimensions       2         OUTCAL CHARACTERISTICS       3         Illumination System       4         Arming System       4         Arming System       4         Arming System Parameters       4         Adming System Parameters       4         Regulatory       5         Reading Performances       6         Test Conditions       7         Avinding scratcher windows       7         Vindow material       7         Software RHSGER Commands       7         Vindow material       7         Software RHSGER Commands       11         Software RHSGER Commands       11         Software RHSGER Commands       11	PREFACE	v
Manual Conventions       v         Outline       v         Technical Support       vi         Detalogic Website Support       vi         Reseller Technical Support       vi         Telephone Technical Support       vi         MECHANICAL CHARACTERISTICS       1         Overview       1         Mereine       2         Dimensions       2         ODTICAL CHARACTERISTICS       3         Mereine       4         Regulatori       4         Regulatori       4         Aiming System       4         Aiming System Parameters       4         Aiming System Parameters       4         Aiming System Parameters       4         Aiming System Parameters       5         Reading Performances       6         Text Conditions       7         Avoiding scratched windows       7         Vindow material       7         Vindow material       7         USB KB Interface       13         USB KB Interface       13         USB KB Interface       13         USB KB Interface       13         USB KB Interface       14         <	About this Manual	v
Outline       v         Technical Support       vi         Reseller Technical Support       vi         Telephone Technical Support       vi         MECHANICAL CHARACTERISTICS       1         Overview       1         Key Parameters       2         Dimensions       2         OPTICAL CHARACTERISTICS       3         MECHANICAL CHARACTERISTICS       3         Illumination System       4         Aiming System       4         Aliming System       4         Aliming System A       4         Aliming System Parameters       4         Aliming System Parameters       4         Aliming System Parameters       4         Aliming System Parameters       5         Reading Performances       6         Test Conditions       7         Vindidow memendations       7         Variding scratched windows       7         Variding scratched windows       7         Variding scratched windows       7         Variding wraperties       7         ELECTRICAL INTEGRATION       9         Overview       9         Host Connector Configuration       10 <t< td=""><td>Manual Conventions</td><td>v</td></t<>	Manual Conventions	v
Technical Support       vi         Datalogic Website Support       vi         Reseller Technical Support       vi         Telephone Technical Support       vi         MECHANICAL CHARACTERISTICS       1         Overview       1         Key Parameters       2         Dimensions       2         OPTICAL CHARACTERISTICS       3         Methanication System       4         Atomic System       4         Atimic System       4         Atimic System       4         Atimic System Parameters       4         Atimic System Parameters       4         Atimic System Parameters       4         Regulatory       5         Reading Performances       6         Test Conditions       7         Atomic System Vindow material       7         Window material       7         ELECTRICAL INTEGRATION       9         Overview       9         Host Connector Configuration       10         HWIT REGRATION       9         USB KB Interface       13         USB KB Interface       13         USB KB Interface       14         Software TRIGGER Commands	Outline	v
Datalogic Website Support	Technical Support	vi
Reseller Technical Support       vi         Telephone Technical Support       vi         MECHANICAL CHARACTERISTICS       1         Overview       1         Key Parameters       2         Dimensions       2         OPTICAL CHARACTERISTICS.       3         Key Parameters       2         Illimination System       4         Regulatory       4         Alming System Parameters       4         Alming System Parameters       4         Regulatory       5         Reading Performances       6         Fest Window Recommendations       7         Evid Window properties       7         ELECTRICAL INTEGRATION       9         Overview       9         Host Connector Configuration       10         HW. TRIGGER Signal       11         Software TRIGGER Commands       11<	Datalogic Website Support	vi
Telephone Technical Support       vi         MECHANICAL CHARACTERISTICS       1         Overview       1         Key Parameters       2         OPTICAL CHARACTERISTICS       3         Millumination System       4         Agegulatory       4         Alming System       4         Alming System Parameters       6         Regulatory       5         Reading Performances       6         Ext Window Roommendations       7         Avoiding Stratched windows       7         Window material       7         ELECTRICAL INTEGRATION       9         Overview	Reseller Technical Support	vi
MECHANICAL CHARACTERISTICS       1         Overview       1         Key Parameters       2         Dimensions       2         OPTICAL CHARACTERISTICS       3         Key Parameters       3         Illumination System       4         Atiming System Parameters       4         Atiming System Parameters       4         Atiming System Parameters       4         Atiming System Parameters       4         Regulatory       5         Reading Performances       6         Test Conditions       6         Exit Window Recommendations       7         Aviding scratched windows       7         Window material       7         Exit Window material       7         Exit window properties       7         ELECTRICAL INTEGRATION       9         Overview       9         Overview       9         West Connector Configuration       10         HW. TRIGGER Signal       11         Software TRIGGER Commands       11         Software TRIGGER Commands       13         USB KB interface       13         USB KB interface       13         USB KB interface <td>Telephone Technical Support</td> <td> vi</td>	Telephone Technical Support	vi
Overview       1         Key Parameters       2         Dimensions       2         OPTICAL CHARACTERISTICS       3         Illumination System       4         Regulatory       4         Aiming System       4         Aiming System Parameters       4         Aiming System Parameters       4         Regulatory       5         Reading Serformances       6         Test Conditions       6         Exit Window Recommendations       7         Avoiding scratched windows       7         Window material       7         ELECTRICAL INTEGRATION       9         Overview       9         Host Connector Configuration       10         HW, TRIGGER Rommands       11         SOFTWARE FEATURES       13         USB KØ Interface       13 <t< td=""><td>MECHANICAL CHARACTERISTICS</td><td>1</td></t<>	MECHANICAL CHARACTERISTICS	1
Key Parameters       2         Dimensions       2         OPTICAL CHARACTERISTICS       3         Key Parameters       3         Illumination System       4         Regulatory       4         Aiming System       4         Aiming System Parameters       4         Aiming System Parameters       4         Regulatory       5         Reading Performances       5         Test Conditions       6         Exit Window Recommendations       7         Window material       7         Window material       7         ELECTRICAL INTEGRATION       9         Overview       9         Host Connector Configuration       10         HW, RIGGER Signal       11         SofTWARE FEATURES       13         USB K0 interface       13         USB K0 interface       13         USB K0 interface       13         USB K0 interface       13         USB COM driver and how it relates to the two interfaces:       13         USB K0 interface       13         USB K1 interface       14         Preducti DSEQ420       21         Preducti DSEQ420       21<	Overview	
Dimensions       2         OPTICAL CHARACTERISTICS       3         Key Parameters       3         Illumination System       4         Ageulatory       4         Aliming System       4         Aliming System       4         Aliming System Parameters       4         Aliming System Parameters       4         Regulatory       5         Reading Performances       6         Test Conditions       6         Exit Window Recommendations       7         Avoiding scratched windows       7         Window maternal       7         Exit Window properties       7         Electriccal INTEGRATION       9         Overview       9         Host Connector Configuration       10         HW_ TRIGGER Signal       11         Software TRIGGER Commands       11         Software RIGGER Commands       11         Software RIGGER Signal       13         USB KB Interface       14         Product: DSE0420	Key Darameters	
OPTICAL CHARACTERISTICS       3         Key Parameters       3         Illumination System       4         Aggulatory       4         Aiming System       4         Aiming System Parameters       4         Aiming System Parameters       4         Regulatory       5         Reading Performances       66         Test Conditions       7         Avoiding scratched windows       7         Window Recommendations       7         Exit Window Recommendations       7         Window material       7         Exit Window properties       7         ELECTRICAL INTEGRATION       9         Overview       9         Host Connector Configuration       10         HW_TRIGGER Signal       11         Software TRIGGER Commands       11         Software RIGGER Commands       11         Software RIGGER Commands       11         VB KB Interface:       13         USB KB Interface:       13         USB KB Interface:       13         USB KB Interface:       14         QUALITY AND RELIABILITY       17         REGULATORY & SAFETY       19         MTBF P	New Palaneters	2
OPICLUCHARACLERISTICS       3         Key Parameters       3         Illumination System       4         Arining System       4         Alming System       4         Alming System       4         Alming System       4         Alming System Parameters       4         Regulatory       5         Reading Performances       6         Test Conditions       6         Exit Window Recommendations       7         Avoiding scratched windows       7         Window material       7         ELECTRICAL INTEGRATION       9         Overview       9         Host Connector Configuration       10         HWTRIGGER Signal       11         Software TRIGGER Commands       11         Software TRIGGER Commands       13         USB KB Interface:       13         USB KD Interface:       14         QUALITY AND RELIABILITY       17         REGULATORY & SAFETY       19         MTBF PREDICTION (CALCULATED)		2
Rey Parameters       3         Illumination System       4         Regulatory       4         Aiming System       4         Aiming System Parameters       4         Aiming System Parameters       4         Regulatory       5         Reading Performances       66         Test Conditions       6         Exit Window Recommendations       7         Avoiding scratched windows       7         Window material       7         Exit Window material       7         Exit window properties       7         Exit window properties       7         Provide methods       9         Overview       9         Host Connector Configuration       10         HW. TRIGGER Signal       11         Software TRIGGER Commands       11         Software TRIGGER Commands       11         Software TRIGGER Commands       11         VIS BK Interface       13         USB KB Interface       13         USB KB Interface       13         USB KB Interface       13         USB KD Mirter and how it relates to the two interfaces:       13         Firmware and configuration updates:       14 <td>OPTICAL CHARACTERISTICS</td> <td></td>	OPTICAL CHARACTERISTICS	
Illumination System       4         Regulatory       4         Aiming System Parameters       4         Aiming System Parameters       4         Regulatory       5         Reading Performances       6         Test Conditions       6         Exit Window Recommendations       7         Avoiding scratched windows       7         Window material       7         ELECTRICAL INTEGRATION       9         Overview       9         Host Connector Configuration       10         HW, TRIGGER Signal       11         Software TRIGGER Commands       11         VSB COM driver and how it relates to the two interfaces:       13         USB COM driver and how it relates to the two interfaces       13         WIBF PREDICTION (CALCULATED)       21         Product: DSE0420       21         System MTBE:       21         Prediction Parameters       21 </td <td>Key Parameters</td> <td></td>	Key Parameters	
Hegulatory       4         Aliming System       4         Aliming System Parameters       4         Aliming System Parameters       4         Aliming System Parameters       4         Regulatory       5         Reading Performances       6         Test Conditions       7         Avoiding scratched windows       7         Avoiding scratched windows       7         Exit Window Recommendations       7         Exit window properties       7         ELECTRICAL INTEGRATION       9         Overview       9         Host Connector Configuration       10         HW_TRIGGER Signal       11         Software TRIGGER Commands       11         Software TRIGGER Commands       11         Software and how it relates to the two interfaces       13         USB KB interface       13         USB KB interface       13         Firmware and configuration updates:       14         QUALITY AND RELIABILITY       17         REGULATORY & SAFETY       19         MTBF PREDICTION (CALCULATED)       21         Product: DSE0420       21         System MDF:       21         Product: DSE042	Illumination System	
Aiming Pattern       4         Aiming System Parameters       4         Aiming System Parameters       4         Regulatory       5         Reading Performances       6         Test Conditions       6         Exit Window Recommendations       7         Avoiding scratched windows       7         Window material       7         ELECTRICAL INTEGRATION       9         Overview       9         Host Connector Configuration       10         HW_TRIGGER Signal       11         Software TRIGGER Commands       11         Software TRIGGER Commands       13         USB KB Interface:       13         USB KB Interface: <td>Regulatory</td> <td>4</td>	Regulatory	4
Aming System Parameters	Aiming System	
Aming System Parameters	Aiming Pattern	4
Regulatory       .5         Reading Performances       .6         Test Conditions       .6         Exit Window Recommendations       .7         Avoiding scratched windows       .7         Window material       .7         Exit window properties       .7         ELECTRICAL INTEGRATION       .9         Overview       .9         Host Connector Configuration       .10         HW_TRIGER Signal       .11         Software TRIGGER Commands       .11         Software TRIGGER Commands       .13         USB -COM driver and how it relates to the two interfaces:       .13         USB-COM driver and how it relates to the two interfaces:       .13         USB-COM driver and how it relates to the two interfaces:       .14         QUALITY AND RELIABILITY.       .17         REGULATORY & SAFETY       .19         MTBF PREDICTION (CALCULATED)       .21         System MTBF:       .21         Prediction Parameters:       .21         System Model:       .22         MECHANICAL DRAWINGS       .23         Overall Dimensions       .24         Optical features       .25         Exit Window Positioning       .26 <t< td=""><td>Aiming System Parameters</td><td>4</td></t<>	Aiming System Parameters	4
Heading Performances       6         Test Conditions       6         Exit Window Recommendations       7         Avoiding scratched windows       7         Window material       7         Exit window properties       7         ELECTRICAL INTEGRATION       9         Overview       9         Host Connector Configuration       10         HW, TRIGERE Signal       11         Software TRIGGER Commands       11         Software TRIGGER Commands       13         USB-COM driver and how it relates to the two interfaces:       13         USB-COM driver and how it relates to the two interfaces:       14         QUALITY AND RELIABILITY       17         REGULATORY & SAFETY       19         MTBF PREDICTION (CALCULATED)       21         Prediction Parameters:       21         Prediction Parameters:       21         Environmental Conditions:       21         System MTBF:       21         Prediction Parameters:       21         Environmental Conditions:       21         System Middel:       22         Assembly Calculation Criteria:       22         MECHANICAL DRAWINGS       24         Overall Dimensions <td>Regulatory</td> <td>5</td>	Regulatory	5
Iest Conditions       7         Exit Window Recommendations       7         Avoiding scratched windows       7         Window material       7         Exit window properties       7         EleCTRICAL INTEGRATION.       9         Overview       9         Host Connector Configuration       10         HW_TRIGGER Signal       11         Software TRIGGER Commands       11         Software TRIGGER Commands       13         USB-COM driver and how it relates to the two interfaces:       13         USB-COM driver and how it relates to the two interfaces:       14         QUALITY AND RELIABILITY.       17         REGULATORY & SAFETY.       19         MTBF PREDICTION (CALCULATED)       21         System MTBF:       21         Preduct: DSE0420       21         System Model:       22         Assembly Calculation Criteria:       22         MECHANICAL DRAWINGS       22         Overall Dimensions       24         Optical features       25         Exit Window Positioning       26         Interface Connector Characteristics & Requirements       27	Reading Performances	6
Exit Window Recommendations       7         Avoiding scratched windows       7         Window material       7         Exit window properties       7         ELECTRICAL INTEGRATION.       9         Overview       9         Host Connector Configuration       10         HW_TRIGGER Signal       11         Software TRIGGER Commands       11         Software TRIGGER Commands       11         Software TRIGGER Commands       13         USB KB interface:       13         USB KB interface:       13         USB KB interface:       13         USB KB interface:       14         QUALITY AND RELIABILITY       17         REGULATORY & SAFETY       19         MTBF PREDICTION (CALCULATED)       21         Product: DSE0420       21         System MTBF:       21         Prediction Parameters:       21         System MTBF:       22         Assembly Calculation Criteria:       22         MECHANICAL DRAWINGS       23         Overall Dimensions       24         Optical features       25         Exit Window Positioning       26         Interface Connector Characteristics & Requi	lest Conditions	6
Avoiding scratched windows	Exit Window Recommendations	
Window material       /         Exit window properties       7         ELECTRICAL INTEGRATION       9         Overview       9         Host Connector Configuration       10         HW_TRIGGER Signal       11         Software TRIGGER Commands       11         Software TRIGGER Commands       13         USB KB interface:       13         USB KB interface:       13         USB KB interface:       13         USB COM driver and how it relates to the two interfaces:       13         Firmware and configuration updates:       14         QUALITY AND RELIABILITY       17         REGULATORY & SAFETY       19         MTBF PREDICTION (CALCULATED)       21         Product: DSE0420       21         System MTBF:       21         Prediction Parameters:       21         Prediction Parameters:       21         System Model:       22         Assembly Calculation Criteria:       22         MECHANICAL DRAWINGS       23         Overall Dimensions       24         Optical features       25         Exit Window Positioning       26         Interface Connector Characteristitics & Requirements       27	Avoiding scratched windows	/
ELECTRICAL INTEGRATION       9         Overview       9         Host Connector Configuration       10         HW_TRIGGER Signal       11         Software TRIGGER Commands       11         SOFTWARE FEATURES       13         USB-COM driver and how it relates to the two interfaces:       13         USB-COM driver and how it relates to the two interfaces:       14         Firmware and configuration updates:       14         QUALITY AND RELIABILITY.       17         REGULATORY & SAFETY       19         MTBF PREDICTION (CALCULATED)       21         Prediction Parameters:       21         System MTBF:       21         System Model:       22         Assembly Calculation Criteria:       22         MECHANICAL DRAWINGS       22         Overall Dimensions       24         Optical features       25         Exit Window Positioning       26         Interface Connector Characteristics & Requirements       26	Window material	/
ELECTRICAL INTEGRATION       9         Overview       9         Host Connector Configuration       10         HW_TRIGGER Signal       11         Software TRIGGER Commands       11         SOFTWARE FEATURES       13         USB KB interface:       13         USB-COM driver and how it relates to the two interfaces:       13         Firmware and configuration updates:       14         QUALITY AND RELIABILITY       17         REGULATORY & SAFETY       19         MTBF PREDICTION (CALCULATED)       21         Product: DSE0420       21         System MTBF:       21         Prediction Parameters:       21         Environmental Conditions:       21         System Model:       22         Assembly Calculation Criteria:       22         MECHANICAL DRAWINGS       23         Overall Dimensions       24         Optical features       25         Exit Window Positioning       26         Interface Connector Characteristics & Requirements       27	Exit window properties	/
Overview9Host Connector Configuration10HW_TRIGGER Signal11Software TRIGGER Commands11Software TRIGGER Commands13USB KB interface:13USB KB interface:13USB-COM driver and how it relates to the two interfaces:13Firmware and configuration updates:14QUALITY AND RELIABILITY.17REGULATORY & SAFETY19MTBF PREDICTION (CALCULATED)21Product: DSE042021System MTBF:21Product: DSE042021System Model:22Assembly Calculation Criteria:22MECHANICAL DRAWINGS23Overall Dimensions24Optical features25Exit Window Positioning26Interface Connector Characteristics & Requirements27	ELECTRICAL INTEGRATION	9
Host Connector Configuration10HW_TRIGGER Signal11Software TRIGGER Commands11Software TRIGGER Commands13USB KB interface:13USB-COM driver and how it relates to the two interfaces:13Firmware and configuration updates:14QUALITY AND RELIABILITY.17REGULATORY & SAFETY19MTBF PREDICTION (CALCULATED)21Product: DSE042021System MTBF:21Product: DSE042021System Model:21System Model:21System Model:22Assembly Calculation Criteria:22MECHANICAL DRAWINGS23Overall Dimensions24Optical features25Exit Window Positioning26Interface Connector Characteristics & Requirements27Zonne Connector Characteristics & Requirements27	Overview	9
HW_TRIGGER Signal       11         Software TRIGGER Commands       11         SOFTWARE FEATURES       13         USB KB interface:       13         USB-COM driver and how it relates to the two interfaces:       13         Firmware and configuration updates:       14         QUALITY AND RELIABILITY       17         REGULATORY & SAFETY       19         MTBF PREDICTION (CALCULATED)       21         Product: DSE0420       21         System MTBF:       21         Prediction Parameters:       21         System MTBF:       21         System Model:       22         Assembly Calculation Criteria:       22         MECHANICAL DRAWINGS       23         Overall Dimensions       24         Optical features       25         Exit Window Positioning       26         Interface Connector Characteristics & Requirements       26	Host Connector Configuration	10
Software TRIGGER Commands       11         SOFTWARE FEATURES       13         USB KB interface:       13         USB-COM driver and how it relates to the two interfaces:       13         Firmware and configuration updates:       14         QUALITY AND RELIABILITY       17         REGULATORY & SAFETY       19         MTBF PREDICTION (CALCULATED)       21         Product: DSE0420       21         System MTBF:       21         Prediction Parameters:       21         System MTBF:       21         System MOdel:       22         Assembly Calculation Criteria:       22         MECHANICAL DRAWINGS       23         Overall Dimensions       24         Optical features       25         Exit Window Positioning       26         Interface Connector Characteristics & Requirements       27	HW_TRIGGER Signal	11
SOFTWARE FEATURES       13         USB KB interface:       13         USB-COM driver and how it relates to the two interfaces:       13         Firmware and configuration updates:       14         QUALITY AND RELIABILITY.       17         REGULATORY & SAFETY       19         MTBF PREDICTION (CALCULATED)       21         Product: DSE0420       21         System MTBF:       21         Prediction Parameters:       21         Environmental Conditions:       21         System Model:       22         Assembly Calculation Criteria:       22         MECHANICAL DRAWINGS       23         Overall Dimensions       24         Optical features       25         Exit Window Positioning       26         Interface Connector Characteristics & Requirements       27	Software TRIGGER Commands	11
USB KB interface:       13         USB-COM driver and how it relates to the two interfaces:       13         Firmware and configuration updates:       14         QUALITY AND RELIABILITY.       17         REGULATORY & SAFETY       19         MTBF PREDICTION (CALCULATED)       21         Product: DSE0420       21         System MTBF:       21         Prediction Parameters:       21         Environmental Conditions:       21         System Model:       22         Assembly Calculation Criteria:       22         MECHANICAL DRAWINGS       23         Overall Dimensions       24         Optical features       25         Exit Window Positioning       25         Exit Window Positioning       26         Interface Connector Characteristics & Requirements       27	SOFTWARE FEATURES	13
USB-COM driver and how it relates to the two interfaces:	USB KB interface:	
Firmware and configuration updates:       14         QUALITY AND RELIABILITY.       17         REGULATORY & SAFETY.       19         MTBF PREDICTION (CALCULATED)       21         Product: DSE0420       21         System MTBF:       21         Prediction Parameters:       21         Environmental Conditions:       21         System Model:       22         Assembly Calculation Criteria:       22         MECHANICAL DRAWINGS       24         Optical features       25         Exit Window Positioning       26         Interface Connector Characteristics & Requirements       27	USB-COM driver and how it relates to the two interfaces:	
QUALITY AND RELIABILITY       17         REGULATORY & SAFETY       19         MTBF PREDICTION (CALCULATED)       21         Product: DSE0420       21         System MTBF:       21         Prediction Parameters:       21         Environmental Conditions:       21         System Model:       22         Assembly Calculation Criteria:       22         MECHANICAL DRAWINGS       24         Overall Dimensions       24         Optical features       25         Exit Window Positioning       26         Interface Connector Characteristics & Requirements       27	Firmware and configuration updates:	14
REGULATORY & SAFETY       19         MTBF PREDICTION (CALCULATED)       21         Product: DSE0420       21         System MTBF:       21         Prediction Parameters:       21         Environmental Conditions:       21         System Model:       22         Assembly Calculation Criteria:       22         MECHANICAL DRAWINGS       24         Overall Dimensions       24         Optical features       25         Exit Window Positioning       26         Interface Connector Characteristics & Requirements       27		17
REGULATORY & SAFETY19MTBF PREDICTION (CALCULATED)21Product: DSE042021System MTBF:21Prediction Parameters:21Environmental Conditions:21System Model:22Assembly Calculation Criteria:22MECHANICAL DRAWINGS23Overall Dimensions24Optical features25Exit Window Positioning26Interface Connector Characteristics & Requirements27		
MTBF PREDICTION (CALCULATED)       21         Product: DSE0420       21         System MTBF:       21         Prediction Parameters:       21         Environmental Conditions:       21         System Model:       22         Assembly Calculation Criteria:       22         MECHANICAL DRAWINGS       23         Overall Dimensions       24         Optical features       25         Exit Window Positioning       26         Interface Connector Characteristics & Requirements       27	REGULATORY & SAFETY	19
Product: DSE042021System MTBF:21Prediction Parameters:21Environmental Conditions:21System Model:22Assembly Calculation Criteria:22MECHANICAL DRAWINGS23Overall Dimensions24Optical features25Exit Window Positioning26Interface Connector Characteristics & Requirements27	MTBF PREDICTION (CALCULATED)	21
System MTBF:       21         Prediction Parameters:       21         Environmental Conditions:       21         System Model:       22         Assembly Calculation Criteria:       22         MECHANICAL DRAWINGS       23         Overall Dimensions       24         Optical features       25         Exit Window Positioning       26         Interface Connector Characteristics & Requirements       27	Product: DSE0420	21
Prediction Parameters:       21         Environmental Conditions:       21         System Model:       22         Assembly Calculation Criteria:       22         MECHANICAL DRAWINGS       23         Overall Dimensions       24         Optical features       25         Exit Window Positioning       26         Interface Connector Characteristics & Requirements       27	System MTBF:	21
Environmental Conditions: 21 System Model: 22 Assembly Calculation Criteria: 22 MECHANICAL DRAWINGS 23 Overall Dimensions 24 Optical features 25 Exit Window Positioning 26 Interface Connector Characteristics & Requirements 27	Prediction Parameters:	21
System Model:	Environmental Conditions:	21
Assembly Calculation Criteria: 22 MECHANICAL DRAWINGS 23 Overall Dimensions 24 Optical features 25 Exit Window Positioning 26 Interface Connector Characteristics & Requirements 27	System Model:	22
MECHANICAL DRAWINGS       23         Overall Dimensions       24         Optical features       25         Exit Window Positioning       26         Interface Connector Characteristics & Requirements       27	Assembly Calculation Criteria:	22
Overall Dimensions	MECHANICAL DRAWINGS	73
Optical features	Overall Dimensions	<b>2</b> 7/-
Exit Window Positioning	Ontical features	24
Interface Connector Characteristics & Requirements	Exit Window Positioning	
	Interface Connector Characteristics & Requirements	

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- Agreement may not be changed, amended, or modified except by written document signed by Datalogic.
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- 11.5 Attorneys' Fees. In the event an action is brought to enforce the terms and conditions of this Agreement, the prevailing party shall be entitled to reasonable attorneys' fees, both at trial and on appeal.

# Preface

#### **About this Manual**

This Integration Guide is provided to give instruction, opto-mechanical details, and design considerations to integrate the DSE0420 model (designated as "scan engine" or "OEM scan engine" in this manual) specifically into equipment-integrated scanning applications.

#### **Manual Conventions**

The following conventions are used in this document:

The symbols listed below are used in this manual to notify the reader of key issues or procedures that must be observed when using the reader:



Notes contain information necessary for properly diagnosing, repairing and operating the reader.



The CAUTION symbol advises you of actions that could damage equipment or property.

#### Outline

Preface (this chapter) presents information about manual conventions and contact data.

Chapter 1. Mechanical Characteristics provides information about physical and performance characteristics.

Chapter 2. Optical Characteristics.

Chapter 3. Electrical Integration offers information about electrical components.

Chapter 4. Software Features describes software commands.

Chapter 5. Quality and Reliability

Chapter 6. Regulatory & Safety environmental and regulatory specifications. Appendix A, MTBF Prediction (Calculated) lists as well as environmental and regulatory specifications.

Appendix B, Mechanical Drawings

#### **Technical Support**

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## Chapter 1 Mechanical Characteristics

#### **Overview**

DSE0420 SCAN ENGINE

**Imager module** 





(\*) cable is shown for reference only, it is not included in the assembly and must be provided by the integrator



(\*) cable is shown for reference only, it is not included in the assembly and must be provided by the integrator

#### **Key Parameters**

Parameter	Value
Weight (DSE0420)	20 g
Max Height (Beeper board not included)	13.65 mm
Max Width (Beeper board not included)	40.10 mm
Max Length (Beeper board not included)	47.86 mm

#### Dimensions

See Mechanical Drawings, starting on page 23 for further details on mechanical features.

## Chapter 2 Optical Characteristics

#### **Key Parameters**

Parameter	Value
Optical Format	1/3-inch
Active Imager Size	4.51mm(H) x 2.88mm(V) 5.35mm diagonal
Active Pixels	752H x 480V
Illumination System	LED source White emission (wavelength = 400-750 nm) IEC 62471 - EXEMPT RISK GROUP
Aiming System	Laser source Red emission (wavelength = 630-680 nm) Pulsed source: maximum lamp duration 15ms, repetition rate 16.6 ms Maximum emitted power: 1 mW IEC 60825 - CLASS 2 LASER PRODUCT
Tilt Tolerance	Up to $\pm$ 360°
Pitch Tolerance	± 65°
Skew Tolerance	± 60°
Field of View	40° H x 26° V

#### Illumination System

The Illumination System is comprised of two white LEDs and non-imaging optics designed to provide first-class reading performances, even in total darkness.

#### Regulatory

EN/IEC 62471 (exempt)

#### **Aiming System**

The aiming system is based on a 650nm laser diode and related optics. It projects a highly visible 4-Dot aimer with center-cross for targeted scanning.



#### **Aiming Pattern**

The central cross represents the center of the field of view, while the four dots show the boundaries of the field of view.





#### **Aiming System Parameters**

Wavelength	630-680 nm
Beam Divergence	35° (horizontal) x 25° (vertical) – see drawings on page 25
Maximum pulse duration	15ms
Repetition rate	16.6ms
Maximum output power	1mW
Laser aperture	See drawings on page 25

#### Regulatory

- EN/IEC 60825-1:2007 (class 2)
- 21 CFR 1040 (CDRH) (class II)



#### Figure 2. Regulatory label

LASER LIGHT - DO NOT STARE INTO BEAM CLASS 2 LASER PRODUCT OUTPUT RADIATION 1 mW MAX. EMITTED WAVE LENGTH 630~680 nm 15 ms PULSE IEC60825-1:2007

> CAUTION-CLASS 2 LASER LIGHT WHEN OPEN AVOID EXPOSURE-LASER LIGHT IS EMITTED FROM THE APERTURE

#### DO NOT STARE INTO BEAM



This product complies with FDA rule 21 CFR Subchapter J in effect at date of manufacture



#### **Reading Performances**

	Decolution	Distance			
Symbology	fmils]	Guaranteed		Тур	ical
		min [mm]	max [mm]	min [mm]	max [mm]
Code 39	3	Maximum resolution (test at 105 mm)			
Code 39	5	70	190	65	210
EAN13	13	55	360	55	390
Datamatrix	15	45	230	40	250
Code 39	20	FOV limited	470	FOV limited	500

Note 1: see Test Conditions below

Note 2: for additional information on exit window disposal, see Appendix B of this document.

#### **Test Conditions**

All distances are taken on axis from the illumination lenses at the following typical conditions:

- "in open air" means without any interposed transparent or semi-transparent material
- environmental light = 300 lux
- Pitch angle =  $10^{\circ}$
- Skew angle =  $0^{\circ}$
- Tilt angle =  $10^{\circ}$  (1D labels)  $0^{\circ}$  (2D labels)

#### Figure 3. Side view



#### Figure 4. Top view



#### **Exit Window Recommendations**



The use of a double-sided AR coated exit window is strongly recommended.

#### Avoiding scratched windows

Scratches on the exit window can strongly affect the reading performance. It is recommended to use an exit window having a scratch-resistant coating and to position the engine window in a recessed position.

#### Window material

The exit window is an integral part of the imaging system and should be designed and selected to preserve the optical quality of the system. It is recommended to use only cell-cast plastics or optical glass.

Common materials and their characteristics are shown in Table 1 below.

#### Table 1. Exit window materials

Properties	<b>PMMA</b> (cell cast acrylic or polymethyl methacrylic)	<b>CR39</b> (Allyl Diglycol Carbonate)
Optical Quality	Very good	Very good
Surface Hardness	Hard coating required	Hard coating required
Impact Resistance	Good	Good
Chemical / UV Resistance	Susceptible	Susceptible
Ultrasonically Welding	Compatible	Compatible

#### **Exit window properties**

Recommended properties/performance of the exit window are reported in Table 2.

#### Table 2. Exit Window Properties

Characteristics	Requirement
Material	PMMA or CR39 or equivalent
Thickness	1.5mm
Wavefront distortion	0.2 wavelengths peak-to-valley maximum and 0,04 $\lambda$ maximum rms over any 2.0mm diameter within the clear aperture
Clear aperture	To extend to within 1.0mm of edges all around
Surface quality	60/20 scratch/dig
AR coating	<ul> <li>double sided</li> <li>transmittance &gt; 97% minimum within spectrum range 400nm-750nm.</li> <li>reflections max 0,4% per side in the range 620nm-640nm</li> </ul>

## Chapter 3 Electrical Integration

#### **Overview**

 $T_A = 25^{\circ} C$  (unless otherwise noted)

PARA- METER	TEST CONDITIONS		MIN	ТҮР	MAX	UNIT
V <sub>IN</sub>	Input Voltage		4.5	5.0	5.5	V
		Shut down V <sub>POWER_ON</sub> = 0 V		240	400	μA
		In-rush current at Start-up First peak after plug-in		3.25		А
		Duration of In-rush current at Start-up		20		μs
		In-rush charge at Start-up Measured at first cold plug-in		35		μC
	$V_{IN} = 5 V$	Stand-by Scan Mode = Trigger Single		12		mA
I <sub>IN</sub>		Operative - Acquiring w/o Beeping Scan Mode = Trigger Single / Flashing	80	150	200	mA
		Operative - Object Detection Scan Mode = Stand Mode	70	90	110	mA
		Operative - Acquiring w/o Beeping Scan Mode = Stand Mode	60	150	230	mA
		Operative - while Beeping Scan Mode = Trigger Single	40	150	260	mA
		Operative - while Beeping Scan Mode = Flashing / Stand Mode	90	255	415	mA
		USB Suspend		5.5		mA
T <sub>SDN</sub>	$V_{IN} = 5 V$	Shut-Down Time Measured from V <sub>POWER_ON</sub> negative edge to I <sub>IN</sub> = 0 mA		300		ms

#### Host Connector Configuration

The connector used to interface the Scan Engine to the Host's USB hub has the following p/n:

#### MOLEX 51281-0894

 $http://www.molex.com/molex/products/datasheet.jsp?part=active/0512810894\_FFC\_FPC\_CON-NECTORS.xml$ 



Direction		ion				
Pin	USB Hub	Deco der	Signal Name	Notes about Decoder side connector pinout		
8		<b>→</b>	POWER_ON	Connected to BJT-Base with the following net: VBUS POWER_ON 5kΩ SkΩ SkΩ SkΩ SkΩ SkΩ SkΩ SkΩ SkΩ SkΩ S		
7		÷	HW_TRIGGER	Connected to BJT-Base with the following net: $HW_TRIGGER \longrightarrow 10k\Omega \qquad \qquad$		
6		$\rightarrow$	VBUS	External power supply 5V $+/-$ 5%, electrically shorted to Pin #5		
5		$\rightarrow$	VBUS	External power supply 5V $+/-$ 5%, electrically shorted to Pin #6		
4			GND	0V reference, electrically shorted to Pin #1		
3	÷	->	USB D-	Data N, USB differential pair		
2	•	$\rightarrow$	USB D+	Data P, USB differential pair		
1			GND	0V reference, electrically shorted to Pin #4		

#### **Description:**

- POWER\_ON signal can be used by host to switch-on/off the whole Scan Engine: leave it unconnected if not used
- HW\_TRIGGER signal can be used to physically
- issue a "trigger pressure" event to the Scan Engine: leave it unconnected if not used
- VBUS, D+, D- and GND are the standard USB interface lines

#### HW\_TRIGGER Signal

This paragraph describes different ways to drive the HW\_TRIGGER signal in order to instruct the Decoder to start acquisition & decode process. Each of these Scan Modes must be first issued (programmed) to the Decoder before to use it. The current default configuration is "Trigger Single".

In the following pictures, "PRESS" and "RELEASE" words refer to the common meaning of pressing a push button and releasing it in order to obtain a specific behavior. The current release of the Decoder board has the HW\_TRIG-GER signal with the following level meaning:

Level	Meaning
n/c or '0' = GND	PRESS
'1' = VBUS	RELEASE



#### Software TRIGGER Commands

The "PRESS" and "RELEASE" events can be issued also by way of the USB communication port (COM emulation only) and the corresponding commands are listed here below:

Command	ASCII Code	Meaning
Х	88 (58h)	PRESS
Т	84 (54h)	RELEASE

The behavioral description of the Scan Engine is the same as that shown above for HW\_TRIGGER Signal.



## Software Features

The DSE0420 supports the following set of host interfaces:

- USB-KBD (Default) USB keyboard emulation
- USB-COM USB serial port emulation
- USB-Composite USB-KBD + USB-COM

Please refer to the Product Reference Guide for all configuration labels.

#### USB KB interface:

- 1. Basic operation In the USB KB interface (the default interface for the Beta version), the scanner emulates a USB Keyboard. The device enumerates as a keyboard, and subsequently delivers all barcode data to the PC as if it were actually a keyboard. This means that data is delivered to the application which has the "focus" on the PC.
- 2. Limitations:
  - No host command support Keyboard devices are "uni-directional"; that is they send data to the PC, but do not accept commands from the PC. This limits the ability to control the module from any application running on the PC.
  - No ability for module updates given the uni-directional interface, the USB KB interface provides no capability to upgrade firmware or configuration through the host interface.

#### USB-COM driver and how it relates to the two interfaces:

The DL USB-COM driver is supplied by Datalogic, and provides legacy applications the ability to connect to a 'virtual' COM port enumerated by the device during connection to the PC. The driver also provides certain configuration capabilities when used with other Datalogic software. When used with the Composite USB interface, where the device enumerates a 'virtual' COM port along with the USB KB interface, the USB-COM driver provides the connection between special configuration applications and the device. Driver selection upon enumeration is controlled by the USB-COM driver's ".inf" file, which contains a list of accepted VID/PID values. The .inf file is NOT user-mutable; the USB-COM driver has been certified through the Microsoft HCK process and cannot be altered by a user.

1. USB-COM interface (interface 47) – When this interface is selected, the device communicates through a 'virtual' COM port via the DL USB-COM driver. All barcodes are passed to applications through this interface.

The applications must thus handle COM port communication. This may be an approach used for any legacy applications that were originally developed for use with RS232 Communication ports.

- 2. Composite USB interface (interface 4D) When this interface is selected, the device enumerates a 'virtual' COM port along with the USB KB interface. Barcode data is sent to the PC through the USB KB interface, while the USB–COM interface will automatically connect through the DL USB–COM driver. This port is then available for any configuration or updates to F/W that may be required for specific customers, or for the general case of providing new firmware with enhanced capabilities. This process is further described below.
- 3. VID/PID table for both the following table contains the Vendor ID (VID) and Product ID (PID) for each interface:

Interface	l/F number	VID	PID
USB OEM	45h	05F9h	121Fh
USB HID Keyboard	35h	05F9h	221Fh
USB-COM (Microsoft)	47h	05F9h	4204h
USB COM / USB HID Keyboard Composite	4Dh	05F9h	4005h
USB HID Firmware Update with Aladdin	4Bh	05F9h	5204h

4. The Datalogic USB-COM driver will be provided for inclusion in the host's image; there will be no need for users to install the driver on the host. Any subsequent updates that may become available will be han-dled through the software update process, if needed.

#### Firmware and configuration updates:

Firmware and configuration files can be updated on the scanner module when the module is in the USB-COM or Composite interface. Updating firmware or configuration is not a common operation and will only be performed upon occasions where new firmware is required, or a specific customer requires special configuration of the module.

When an update is needed, the tablet image will come pre-loaded with software utilities that provide a method for easy update of the unit. In most cases, the update will be accomplished by the customer's IT department using a batch file or other similar process that can be remotely invoked on the tablet. Such a process will utilize the command line interface available through the Datalogic Remote Management software.

 Brief description of the software stack - The update of either firmware or configuration for the module uses the same process. The update itself is performed by Datalogic's Remote Management software layer, which provides an interface to the device through the USB-COM driver. The remote management software is always resident on the tablet but is only executed when an update is invoked. 2. Instructions for invoking the update(s) – To perform an update, the following instruction is executed from the command line:

C:\<path> cfirmwareupdate <scanner\_name> <"path:filename">

Where:  $\langle nath \rangle = the 1$ 

```
<path> = the location on the tablet where the Datalogic
utilities are installed
<scanner_name> = IntegratedImagingBarcodeScanner
<"path:filename"> = the path to the update file+update
file name
```

- 3. Limitations
  - The module must be in USB-COM or Composite interface; updates are not possible when the module is in the USB KB interface.
  - The module should not be in use by any application. Performing an update to the scan module should only be done when the module is not actively being used by an application.
  - The module should be in an idle state.

## Chapter 5 Quality and Reliability

Test ID	Test	Description		
		<b>Dynamic Shock</b> : 2000 G ± 5% applied via any mounting surface at -30° C and 70° C for a period of 0.85 ± 0.05 msec. 2500 G ± 5% applied via any mounting surface at 23° C for a period of 0.85 ± 0.05 msec		
1	Shock	Vibration		
		20 to 80 Hz Ramp up at 0.04 G <sup>2</sup> /Hz at 3 dB/octave		
		80 to 350 Hz 0.4 G <sup>2</sup> /Hz		
		350 Hz to 2 kHz Ramp down at 0.04 G <sup>2</sup> /Hz at 3 dB/octave		
	Storage Temperature: -40° C to +70° C			
2	Environmental	Operating Temperature: -15° C to +55° C		
		Humidity (non-condensing) $\leq 95\%$		
		The Scan Engine must be shielded from ESD strikes up to $\pm 1$ 5KV with the enclosure.		
4	ESD	To date, testing on the Imager Module has been performed at level of 2,5KV on the connector. The module was tested inside another host product up to 4Kv direct and 8KV air.		
5	MTBF	An MTBF calculation has been completed and is shown in Appendix A		

## Chapter 6 Regulatory & Safety

ltem	Description	
Laser Classification	IEC 60825 - CLASS 2 LASER PRODUCT Maximum emitted power: 1 mW, Emitted wavelength 630–680 nm Pulsed source: maximum lamp duration 15ms, repetition rate 16.6 ms	
Lamp Standard	IEC 62471 Exempt	
Radiated Emissions	EN 55022 / 2010	
Support Documentation	Support documentation is available on request to assist the ODM in their sys- tem submittal to Regulatory and Safety Agencies. Some examples of support documentation are: Laser Safety Classification Calculation Lamp Standard Calculation RoHS documentation	

# Appendix A

## MTBF Prediction (Calculated)

#### Product: DSE0420

#### System MTBF:

DSE0420 MTBF					
Duty Cycle	Operating Temperature 25°C	Operating Temperature 55°C			
100%	218,412 hrs.	60,125 hrs.			
50%	399,416 hrs.	109,785 hrs.			

DSE0420 RAMM				
		-		
Duty Cycle	Operating Temperature 25°C	Operating Temperature 55°C		
100%	0.00334	0.01214		
50%	0.00183	0.00665		

#### **Prediction Parameters:**

Software: Relex Reliability Studio 2008 (Telcordia Method II Case L1)

#### **Environmental Conditions:**

- GM Ground Mobile
- Maximum Ambient Temperature: 55 oC
- Internal Temperature rise 7 oC

#### System Model:

All assemblies in serial mode. All assemblies must function for the system to work.

#### **Assembly Calculation Criteria:**

• All Electronic assembly failure rates calculated from BOM listing using Telcordia model.

DATALOGIC HAS DEMONSTRATED A 99% SUCCESS RATE OF MEETING OR EXCEEDING OUR PREDICTION BASED ON ACTUAL PRODUCT DEMONSTRATED LIFE TEST RESULTS AND ACTUAL FIELD DATA.

Any requests for reliability information on our products are granted with a clear understanding that MTBF/RAMM numbers are design targets. They are based on all available reliability data from preceding product demonstrated life testing and calculated semiconductor failure rates. They do not represent an implied warranty. As with all reliability numbers, infant mortality, early wear-out failures and variations in operating environment are not included.

Date: 5-June-2013 Reliability Engineer: D.A. Hershberger

## Appendix B Mechanical Drawings

This section describes the main mechanical features related to the following key points:

- Overall Dimensions
- Optical features
- Exit Window Positioning
- Interface Connector Characteristics & Requirements

#### **Overall Dimensions**



#### **Optical features**



#### **Exit Window Positioning**



For additional information about the Scan Engine, please refer to the DE2011-DL Integration Guide

#### **Interface Connector Characteristics & Requirements**



#### MOLEX CONNECTOR SPECIFICATION - DOCUMENT NUMBER SD-51281-011 (FOR DETAILED CONNECTOR INFORMATION, REFER TO THE MANUFACTURERS SPECIFICATIONS)







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